

# SHIP – target cooling flow simulations

Preliminary results



Approach: gap-wise, minimize the standard deviation of temperature drop (along the length) – this would imply that heat transfer conditions are the same in all channels.

In general, to calculate the temperature drop in the channel one can use the following equation

$$Q_y = hA (T_s - T_\infty)$$

and solve for  $T_s$ . However, the heat transfer coefficient (HTC),  $h$ , bulk fluid temperature,  $T_\infty$  and dissipated power,  $Q$ , have to be explicitly known. As  $Q$  and  $T_\infty$  can be considered given for our problem, only HTC has to be calculated. HTC is in general a function of dimensionless Nusselt number.

$$h = \frac{k}{D} Nu$$

Nu number in turn depends on Reynolds and Prandtl numbers. The empirical correlation used for calculation of Nu number for flows in ducts was given by Dittus and Boelter and is as follows:

$$Nu_D = 0.023 Re_D^{4/5} Pr^n \quad \text{where} \quad Re = \frac{\rho v_s D}{\mu}.$$

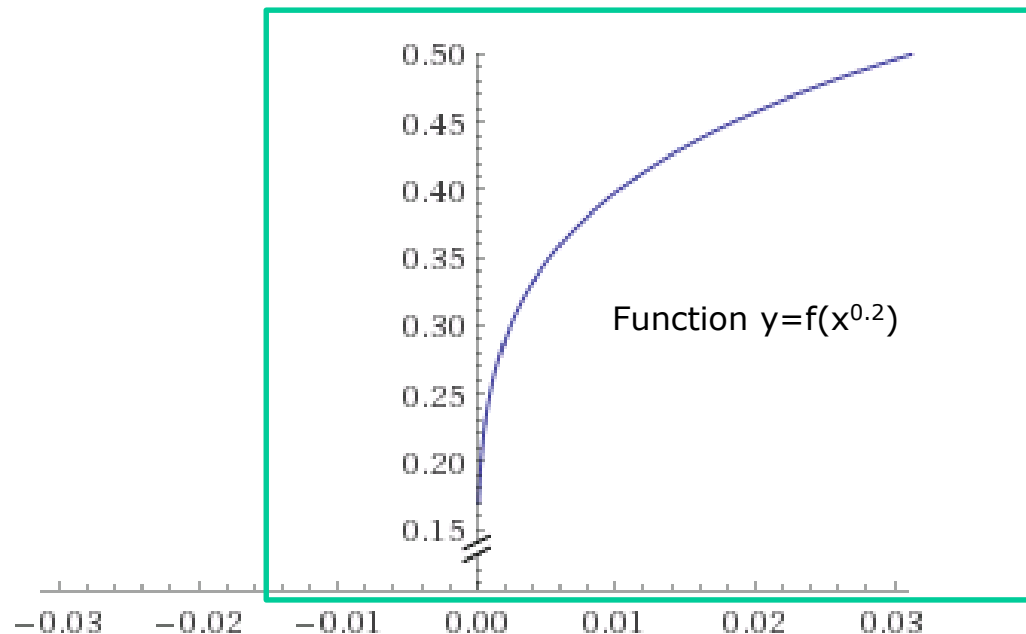
Based on the simulations done for **heat load of 1 pulse uniformly distributed in 7.2 seconds**, the following conclusions can be drawn:

- while theoretically a flow of 4 litres/second is theoretically capable of removing the heat from the system with a water temperature increase of 20 °C, uneven flow distribution across the gaps, as well as boundary layer effects will cause the water to heat up locally by over 300 °C
- The local heat-up effect is less pronounced for a flow of 16 l/s - the maximum local temperature in the channels is between 100 and 140 °C (depending on the manifold setup) and occurs in the middle of the gaps, where water is exposed to highest wall temperatures.
- For a flow of 16 l/s average water temperature in each of the gaps is ca. 25 °C
- Maximum local and average wall temperatures follow the results for water
- For a flow of 16 l/s a pressure drop between 50 (constant manifold cross-section area) to 75 mbar (sloped manifolds) is expected in the system
- All three tested turbulence models (standard k-epsilon, realizable k-epsilon, transition SST) provide similar results\
- A transient simulation accounting for heat load being

Altogether, this shows that the heat transfer coefficient is a function of hydraulic diameter (thus: the gap size as well).

$$h = \frac{k}{D} 0.023 Re^{4/5} Pr^n = f(D^{-0.2}) \Rightarrow T = f(D^{0.2})$$

The problem is that  $f(D^{0.2})$  is an increasing function (as shown in the picture below), thus when the gap size increases, the heat transfer coefficient goes down and the surface temperature increases. Therefore for the stated optimization problem, in spots where heat load is the highest, the gap size would be chosen as small as possible, while in spots where heat load is the lowest, the „ideal” gap size would be as high as possible.



In order to solve the optimization problem, one has to solve a set of 18 non-linear equations. Non-linear solver used (NOMAD) cannot guarantee an optimal solution but it seems to confirm what has been discussed in previous slides.

Assumptions:

- Water at 10 bars, inlet temperature – 25°C, outlet temperature - 125°C
- Heat load uniform over 7.2 seconds (for heat transfer purposes this would require the target surface temperature to be constant during the operation)→ each of the two gaps around a given layer **takes ½ of the heat deposited in the layer.**

The fields highlighted in light corresponding to gaps with lowest heat loads are too big in size (over 1 cm). The gaps highlighted in red (highest heat loads) are determined to be very small by the solver (lower than 1 mm).

Also, almost identical solution was given for a problem, where the gaps were split into 10 equally-sized parts, with water properties assumed to be increasing by 10 degrees from one cell to another. The results were close to the non-discretized approach results (below).

| Gap number                    | 1   | 2   | 3    | 4   | 5   | 6    | 7   | 8   | 9   |
|-------------------------------|-----|-----|------|-----|-----|------|-----|-----|-----|
| Size [mm]                     | 9.4 | 4.2 | 12.2 | 6.5 | 2.4 | 11.3 | 4.0 | 1.3 | 1.8 |
| Heat flux [W/m <sup>2</sup> ] | 47  | 130 | 200  | 260 | 300 | 320  | 480 | 620 | 580 |

| Gap number                    | 10  | 11  | 12  | 13  | 14  | 15  | 16  | 17   | 18   |
|-------------------------------|-----|-----|-----|-----|-----|-----|-----|------|------|
| Size [mm]                     | 3.8 | 1.4 | 1.0 | 0.6 | 0.7 | 6.2 | 8.6 | 12.7 | 12.1 |
| Heat flux [W/m <sup>2</sup> ] | 530 | 610 | 650 | 770 | 740 | 490 | 310 | 140  | 45   |

Under the same assumptions as in analytical considerations, CFD studies have shown, that for the gap with the critical heat load (corresponding to layer 13) a width of 0.5 cm assuming a 0.35 m/s velocity should be sufficient – maximum temperature of water in the gap would then be 90 °C (outlet).

This is also true for the gaps with the critical volumetric heat load (gaps 6 and 7) – in that case the maximum temperature of water in the gap (for a width of 0.5 cm and flow velocity of 0.35 m/s) was calculated to be 70 °C (also at the outlet).

Based on the simulations done for **heat load of 1 pulse uniformly distributed in 7.2 seconds**, the following conclusions can be drawn:

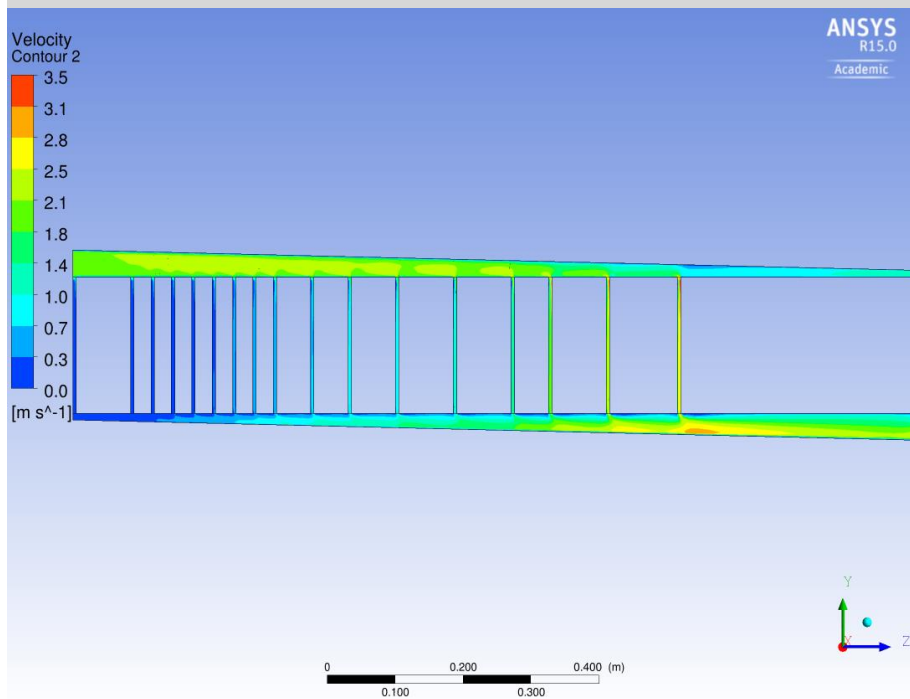
- while a flow of 4 litres/second is theoretically capable of removing the heat from the system with a water temperature increase of 20 °C, uneven flow distribution across the gaps, as well as boundary layer effects will cause the water to heat up locally by over 300 °C
- The local heat-up effect is less pronounced for a flow of 16 l/s - the maximum local temperature in the channels is between 100 and 140 °C and occurs in the middle of the gaps, where water is exposed to highest wall temperatures. This corresponds to a HTC of 10000 – 20000 W/m<sup>2</sup>K
- For a flow of 16 l/s average water temperature in each of the gaps is ca. 27 °C
- Obviously, maximum local and average wall temperatures follow the results for water
- For a flow of 16 l/s a pressure drop between 50 (constant manifold cross-section area) to 75 mbar (sloped manifolds) is expected in the system
- All three tested turbulence models (standard k-epsilon, realizable k-epsilon, transition SST) provide similar results
- **A transient simulation accounting for heat load being non-uniform over 7.2 seconds needs to be investigated in order to understand its influence on the local conditions in the boundary layer**

The influence of having a sloped upper and lower manifolds was investigated.

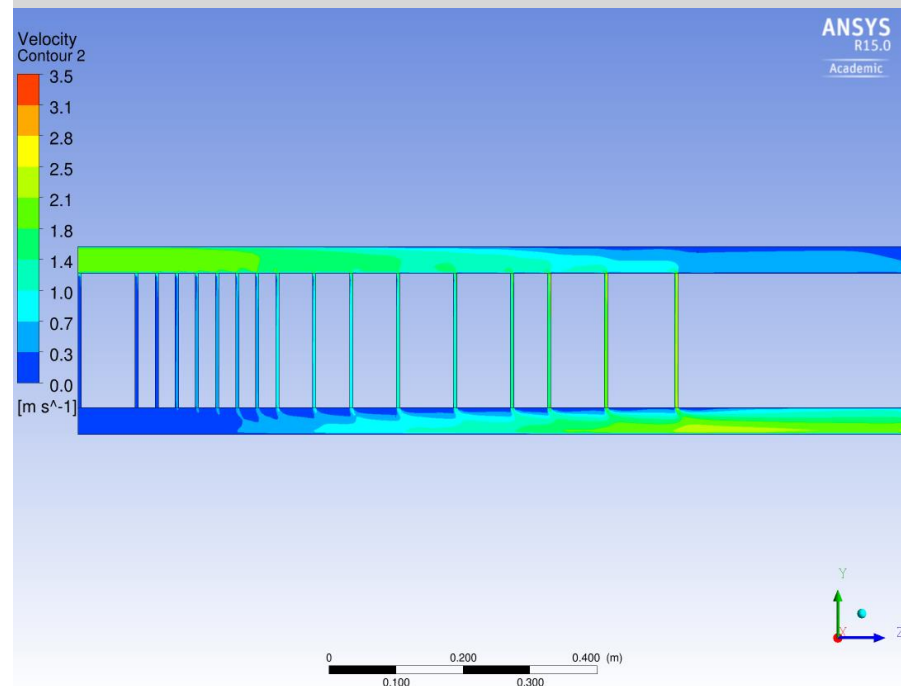
While low velocity case (4 l/s flow) indicated that a constant cross-section manifold could be a superior solution because of more uniform velocity distribution across the gaps, the difference was less pronounced for a 16 l/s case.

One can see that there is little flow at the first gaps compared with the last ones, however we plan to see the effect of having a vertical inlet from the top, instead of a horizontal inlet.

## Sloped manifolds



## Constant cross-section manifolds

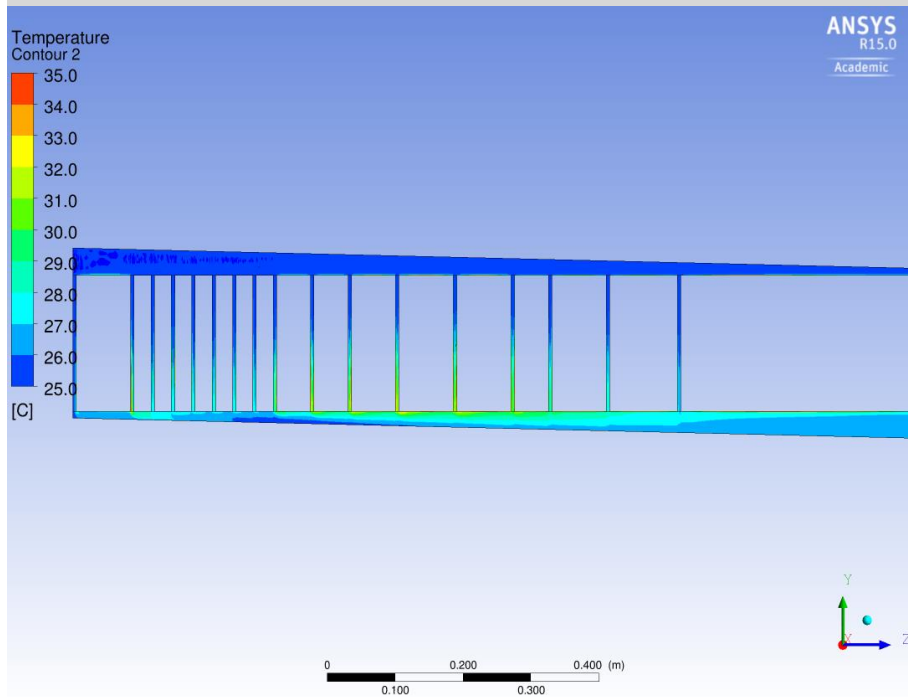


Temperatures at gap exits do not exceed 30 °C, which is a 5 °C heat-up, thus one can view a 16 l/s water flow as sufficient for the uniformly distributed heat load case.

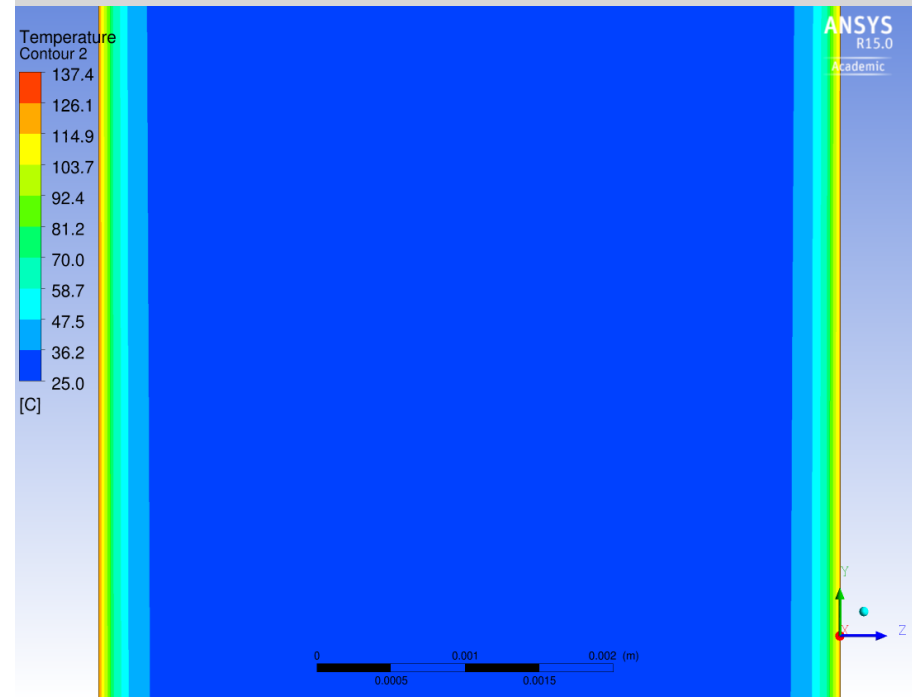
Temperature of water in the boundary layers reaches values as high as 137.4 °C, especially in the center of the gaps, where it encounters highest wall temperatures. This indicates that a transient solution is a necessity, as the wall temperature is expected to fluctuate.

Still, the non-uniform velocity distribution causes a significant difference in the maximum water temperature across the gaps which is between 28 °C (last gap) to 137.4 °C (first gap).

## Temperatures in the gaps



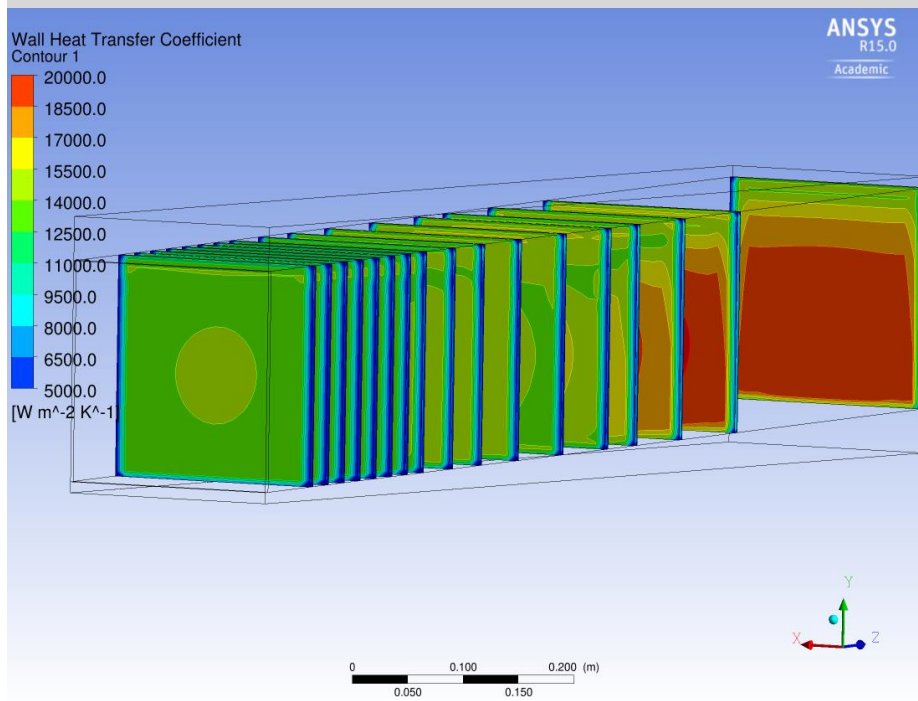
## Close-up at the center of one of the gaps



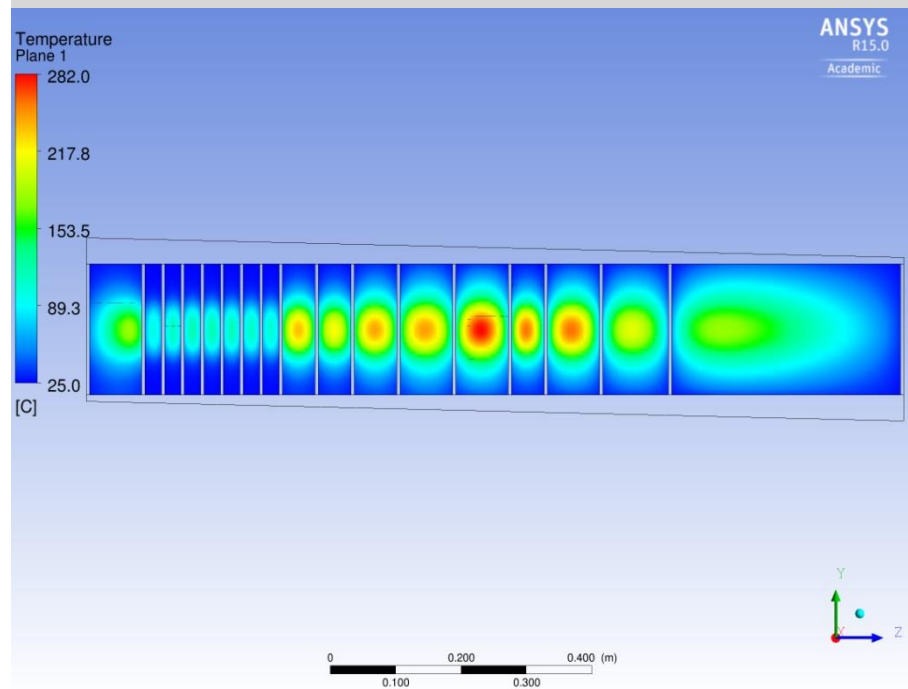
The heat transfer coefficient in the 16 l/s case varies between around 10000 W/m<sup>2</sup>K encountered in the first gaps, where the velocity is the lowest, up to 20000-25000 W/m<sup>2</sup>K in the last gaps with the highest flow velocity.

Under the assumption of uniform heat load over pulse period, the maximum block temperature of 282 °C is observed in block 13.

Heat transfer coefficient



Close-up at the center of one of the gaps



- numerical sensitivity, mesh dependence
- E deposition based gap distribution
- evening velocity distribution in gaps
- transient simulation

Several simulations, both transient and steady-state, were conducted in order to find an appropriate solution for cooling of the SHIP target. The conclusions are as follows:

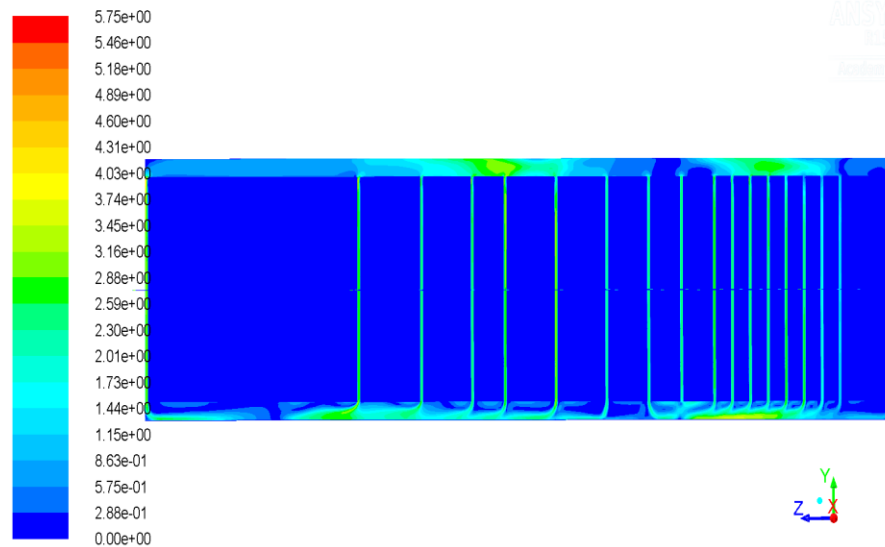
- A system of 4 inlet and 4 outlet pipes, all of 9 cm diameter, seems to be able to make the velocity distribution in the gaps uniform.
- The widths of the gaps are not as crucial to the problem as the distribution of the flow. Bulk fluid temperature remains low for any velocity close to 2 m/s. Gaps thinner than 0.5 cm could also be capable of removing the heat, however the pressure drop will surely affect the velocity distribution in such case.
- With lower flow velocities it is possible to evacuate the heat as well, however boundary layer effects will cause the water to heat up significantly close to the walls and this needs to be tackled by using velocities higher than the analytically derived ones.
- For transient simulations, quasi-steady state of the system is reached after 5 pulses. There is only a slight difference in temperature of water after the 3rd pulse.
- In the transient simulation - the maximum local temperature in the channels stands at 120 °C, corresponding to heat transfer coefficients of ca. 20000 W/m<sup>2</sup>K.
- For a flow of 50 l/s a pressure drop of ca. 160 mbar is expected in the system
- **Mesh independence study needs to be done for transient simulation due to varying heat transfer conditions. Also, temperatures in the gaps could be equalized by assuming a linear relation between heat deposition and gap width.**

After several tested arrangements of the inlet and outlet pipes, 2 transient cases were ran, for flows of 50 and 80 l/s. The arrangement allowed for a singificantly more uniform distribution of velocities in the gaps, thus reducing the maximum recorded temperature.

Note that for simplifcation the inlet and outlets are simulated as squares with sides of 8 cm which corresponds to an area of a pipe of 9 cm inner diameter.

Pictures below show the velocity at the mid-X plane cross-section (vertical cut) for transient simulation after 1 pulse. The velocity scale differs for each of the pictures.

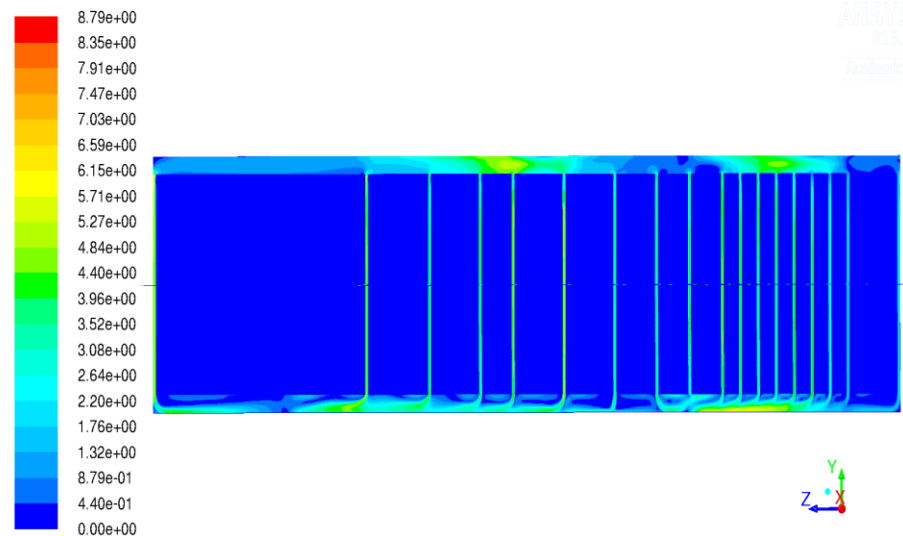
Velocity after 1 pulse – 50 l/s flow



Contours of Velocity Magnitude (m/s) (Time=1.0000e+00)

Jan 21, 2015  
ANSYS Fluent 15.0 (3d, dp, pbns, rke, transient)

Velocity after 1 pulse – 80 l/s flow



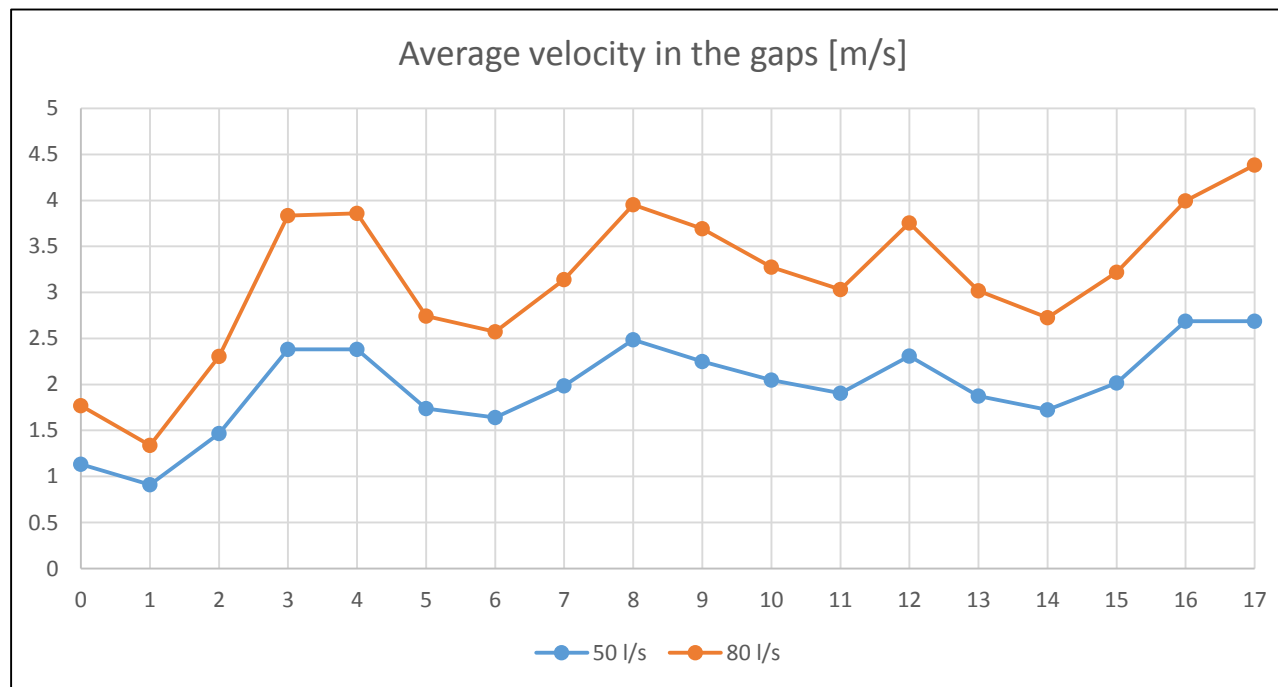
Contours of Velocity Magnitude (m/s) (Time=1.0000e+00)

Jan 21, 2015  
ANSYS Fluent 15.0 (3d, dp, pbns, rke, transient)

The plot below presents the velocity distribution in the gaps. One can immediately see that the graphs follow the same trend, indicating that the conditions change linearly with increase of the flow rate, i.e. if inlet velocity is changed by a factor of 2, it is expected the velocity in the gaps increases by a factor of 2 as well.

For a system of equally sized gaps it is important to have high flow in spots where more heat is deposited, which in our case are, in general, the blocks which are 2.5 cm wide.

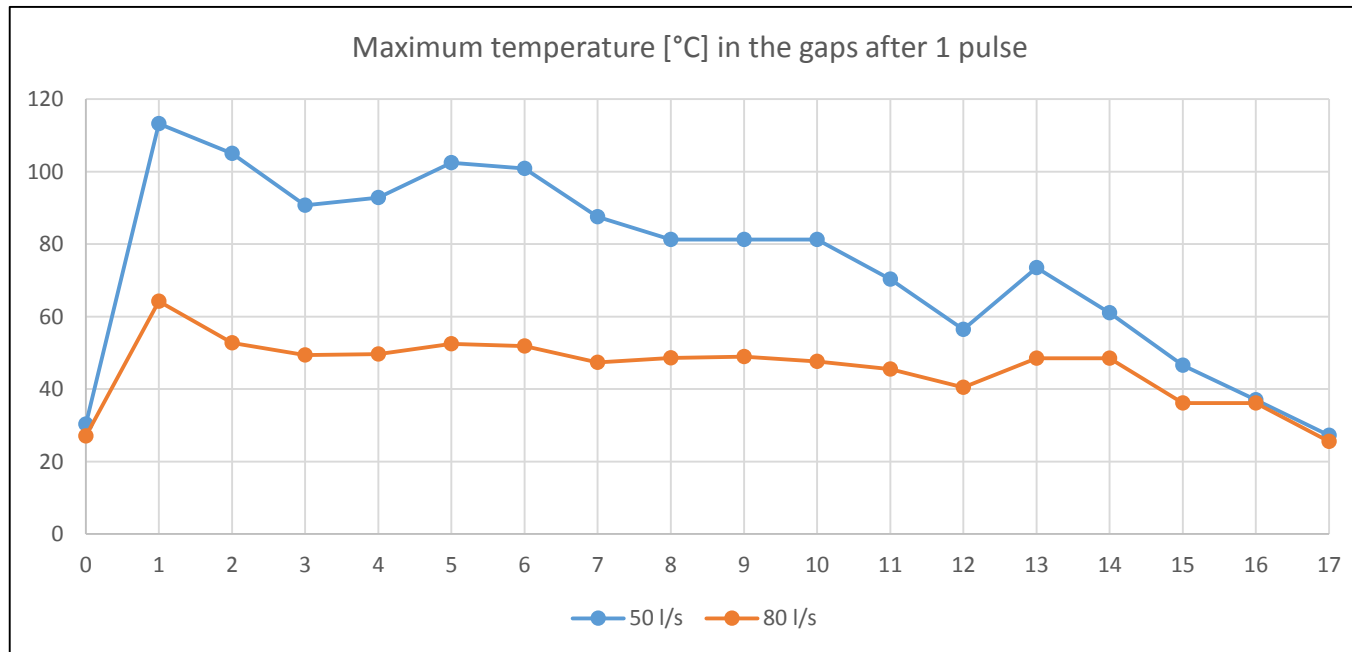
Although block 1 is exposed to the smallest flow, it contains higher heat capacity than the thinner blocks and the flow observed was sufficient to keep it reasonably cooled.



For both flows of 50 and 80 l/s, the temperatures at gap exits are in the range of 0-3 °C, showing that both of these flows are sufficient to keep the system cooled.

Temperature of the coolant in the boundary layers reaches values up to 120 °C, still below the evaporation temperature for water at 10 bar standing at 180 °C.

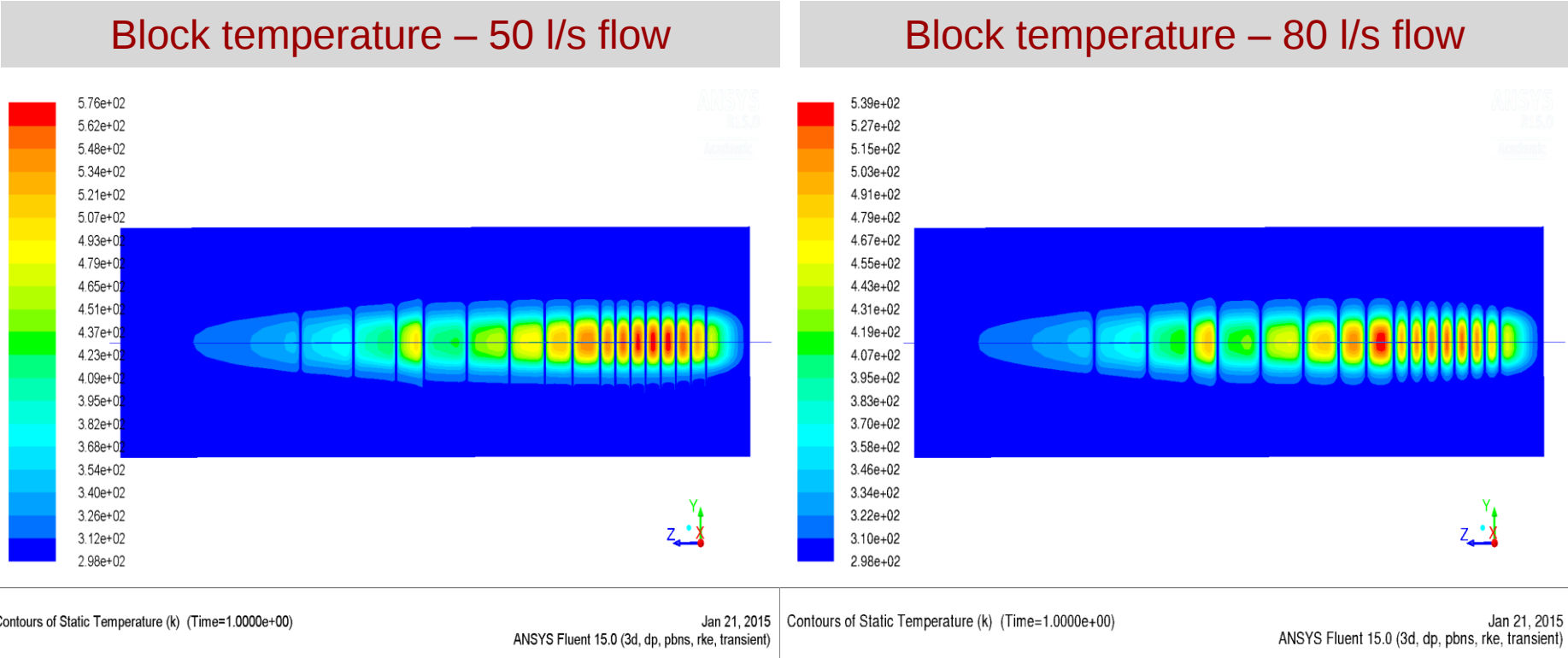
Even though the flow has been significantly uniformized compared to the previously presented results, due to different heat deposition in the blocks, the maximum registered temperature varies between 3 to 100 °C after 1 pulse. Local maximum temperatures were registered for the blocks, which are located in between the inlet pipes, due to the two flows having opposite directions collide and in result the velocity is lower.



The heat transfer coefficient in the 50 l/s case varies between around 15000-20000 W/m²K, with the average being 19000 W/m²K, while for flow of 80 l/s it is slightly higher at 21000 W/m²K.

For the two flows, different blocks are predicted as the ones with highest temperature – in case of the lower flow, it is block 6 at 303 °C, while for the higher – block 9 at 266 °C.

Another simulation with heat deposition averaged over 7.2 seconds and 50 l/s flow showed that the maximum temperature is 271 °C in block 9.



Thank you for your attention!